

# Answer Set Programming with External Source Access

Reasoning Web Summer School 2017



DLVHEX

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# Outline

Background

Answer Set Programs

HEX Programs

Methodology and Modeling

Application Scenarios

The DLVHEX-System

DLVHEX in Practice

Conclusion

# Introduction

- ▶ Answer Set Programming (ASP): recent problem solving approach
- ▶ Term coined by DBLP:conf/iclp/Lifschitz99 [DBLP:conf/iclp/Lifschitz99,lifs-2002], proposed by others at about the same time, e.g. [Marek and Truszczyński, 1999], [Niemelä, 1999]
- ▶ It has roots in KR, logic programming, and nonmonotonic reasoning
- ▶ At an abstract level, relates to Satisfiability (SAT) solving and Constraint Programming (CP)
- ▶ Books: [Baral, 2003], [Gebser *et al.*, 2012], compact survey: [Brewka *et al.*, 2011]

Fall 2016



## ANSWER SET PROGRAMMING ARTICLES

- [5 Answer Set Programming: An Introduction to the Special Issue](#)  
*Gerhard Brewka, Thomas Eiter, Mirosław Truszczyński*
- [7 Answer Sets and the Language of Answer Set Programming](#)  
*Vladimir Lifschitz*
- [13 The Answer Set Programming Paradigm](#)  
*Toini Janhunen, Ilkka Niemelä*
- [25 Grounding and Solving in Answer Set Programming](#)  
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- [69 First Order Logic with Inductive Definitions for Model-Based Problem Solving](#)  
*Maurice Bruynooghe, Marc Denecker, Mirosław Truszczyński*

# Logic Programming – Prolog

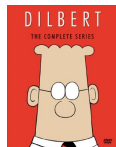
1960s/70s: Logic as a programming language (??)

- ▶ Breakthrough: Robinson's Resolution Principle (1965)

Kowalski (1979): **ALGORITHM = LOGIC + CONTROL**

- ▶ Knowledge for problem solving (LOGIC)
- ▶ “Processing” of the knowledge (CONTROL)

**Prolog = “Programming in Logic”**



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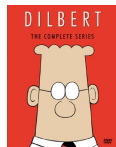
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Example: Dilbert

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man(dilbert).  
person(X) ← man(X).  
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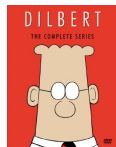
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- ▶ Proofs provide answers, based on SLD resolution
- ▶ Understanding the resolution mechanism is important
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$$\text{reverse}([X|Y], Z) \leftarrow \text{append}(U, [X], Z), \text{reverse}(Y, U). \quad (1)$$

vs

$$\text{reverse}([X|Y], Z) \leftarrow \text{reverse}(Y, U), \text{append}(U, [X], Z). \quad (2)$$

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## Is this truly declarative programming?

# Negation in Logic Programs

Why negation?

- ▶ Natural linguistic concept
- ▶ Facilitates convenient, declarative descriptions (definitions)

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(cont'd)

Modifying the last rule of the Dilbert program, we obtain:

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Two intuitive models:

$$\begin{aligned} M_1 &= \{\text{man}(\text{dilbert}), \text{single}(\text{dilbert})\}, \\ M_2 &= \{\text{man}(\text{dilbert}), \text{husband}(\text{dilbert})\}. \end{aligned}$$

Which one to choose?

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Which one to choose? Answer set semantics: both!

# LP Desiderata

Relieve the programmer from several concerns:

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## “Pure” declarative programming

- ▶ Prolog does not satisfy these desiderata
- ▶ Satisfied by the *answer set semantics* of logic programs

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**Syntax**

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# Answer Set Programs: Syntax

Starting point: *relational signature*  $S = (\mathcal{C}, \mathcal{P}, \mathcal{X})$  of pairwise disjoint sets

- ▶  $\mathcal{C}$  of *constants*,
- ▶  $\mathcal{P}$  of *predicate symbols*  $p/n$  (arity  $n \geq 0$ ), and
- ▶  $\mathcal{X}$  of *variables*

Basic building blocks:

- ▶ *terms* are elements of  $\mathcal{C} \cup \mathcal{X}$
- ▶ *atoms* are formulas  $p(t_1, \dots, t_n)$ , where  $p/n \in \mathcal{P}$
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## Example

Typically,  $S$  is not stated explicitly if it is clear from the context; variables start with upper case letter

- ▶ terms  $X$ ,  $bob$ ,  $123$
- ▶ atoms  $day()$ , written as  $day$ ,  $firstname(bob)$ ,  $reachable(a, Y)$
- ▶ literals  $firstname(bob)$ ,  $day$ ,  $\text{not } day$



# Answer Set Programs: Syntax (cont'd)

Programs consist of rules written in “A if B” form

## Rules and Programs

A *logic program* is a finite set of (disjunctive) rules  $r$  of the form

$$A_1 \vee \dots \vee A_m \leftarrow L_1, \dots, L_n, \quad m, n \geq 0$$

where all  $A_i$  are atoms and all  $L_j$  are literals.

- ▶  $head(r) = \{A_1, \dots, A_m\}$  is the *head* (conclusion)
- ▶  $body(r) = \{L_1, \dots, L_n\}$  is the *body* (premise)

Rules  $r$  with  $body(r) = \emptyset$  are *facts*, and with  $head(r) = \emptyset$  are *constraints*

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## Example

$day \vee night.$

$\leftarrow sunshine, raining.$

$sunshine \leftarrow day, \text{not } raining.$

# Safety and Recursion

## Technical Requirement (by Solvers)

Each variable in a rule  $r$  must occur in  $body(r)$  unnegated (*safety*).

## Example

$r_1 : p(X) \leftarrow q(X, Y), at, \text{not } r(X).$

safe ✓

$r_2 : p(X) \leftarrow \text{not } t(Z).$

unsafe ✗

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## Example: Reachability/Unreachability

$r_1 :$	$reachable(X, Y) \leftarrow connection(X, Y).$
$r_2 :$	$reachable(X, Z) \leftarrow reachable(X, Y), reachable(Y, Z).$
$r_3 :$	$not\_reachable(X, Y) \leftarrow location(X), location(Y), not\ reachable(X, Y).$

- ▶ Rules  $r_1$  and  $r_2$  express reachability (recursion)
- ▶ Rule  $r_3$  expresses *unreachability* on top – not expressible in first-order logic!

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# Semantics

- ▶ Consider *ground* (i.e. *variable-free*) rules and programs
- ▶ This is lifted to arbitrary programs by variable elimination (*grounding*)

## Herbrand Universe, Herbrand Base, Interpretations

Given a relational signature  $S = (\mathcal{C}, \mathcal{P}, \mathcal{X})$ ,

- ▶ the *Herbrand universe*  $HU$  are all ground terms (i.e.  $\mathcal{C}$ ),
- ▶ the *Herbrand base*  $HB$  is the set of all ground atoms wrt.  $S$ ,
- ▶ a (Herbrand) *interpretation* is any set  $I \subseteq HB$ .

Intuitively,  $a \in I$  means  $a$  is true in  $I$ , and false otherwise.

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## Example

$P = \{ \text{friend}(X, Y) \leftarrow \text{friend}(Y, X); \text{happy}(X) \leftarrow \text{friend}(\text{bob}, X); \text{friend}(\text{joy}, \text{bob}) \}$

- ▶  $HU = \{ \text{joy}, \text{bob} \}$
- ▶  $HB = \{ \text{friend}(\text{bob}, \text{bob}), \text{friend}(\text{bob}, \text{joy}),$   
 $\text{friend}(\text{joy}, \text{bob}), \text{friend}(\text{joy}, \text{joy}), \text{happy}(\text{bob}), \text{happy}(\text{joy}) \}$
- ▶  $I = \{ \text{friend}(\text{joy}, \text{bob}), \text{friend}(\text{bob}, \text{joy}), \text{happy}(\text{joy}) \}$

## Semantics (cont'd)

Satisfaction of formulas, programs etc  $\alpha$  in interpretation  $I$ , denoted  $I \models \alpha$ , is defined bottom up

### Satisfaction, Model

An interpretation  $I$  *satisfies* (is a *model* of)

- ▶ a ground atom  $a$ , if  $a \in I$ ;
- ▶ a literal  $\text{not } a$ , if  $I \not\models a$ ;
- ▶ a conj.  $L_1, \dots, L_n$  of ground literals,  $I \models L_i$  for  $i = 1, \dots, n$ ;
- ▶ a disj.  $A_1 \vee \dots \vee A_m$  of ground atoms if  $I \models A_k$  for some  $1 \leq k \leq m$ ;
- ▶ a ground rule  $r$ , if  $I \models \text{body}(r)$  implies that  $I \models \text{head}(r)$ ;
- ▶ a ground program  $P$ , if  $I \models r$  for each rule  $r \in P$ .



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### Example (cont'd)

$I = \{\text{friend}(\text{joy}, \text{bob}), \text{friend}(\text{bob}, \text{joy}), \text{happy}(\text{joy})\}$

- ▶  $I \models \text{happy}(\text{joy}); \quad I \not\models \text{happy}(\text{bob})$
- ▶  $I \models \text{friend}(\text{bob}, \text{joy}) \leftarrow \text{friend}(\text{joy}, \text{bob})$
- ▶  $I \models \text{happy}(\text{joy}) \vee \text{happy}(\text{bob}) \leftarrow \text{friend}(\text{bob}, \text{joy}), \text{not friend}(\text{joy}, \text{bob})$

## Semantics (cont'd)

### Example

$$P = \{ b. \quad a \leftarrow b. \quad c \leftarrow d. \}$$

- ▶  $I_1 = \{b, a\}$  is a model of  $P$
- ▶  $I_2 = \{b, a, c\}$  is a model of  $P$  as well

why should  $c$  being true in  $I_2$  be accepted?

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### CWA Rationale

- ▶ Respect reit-78's [reit-78] *Closed World Assumption (CWA)*: If  $c$  is not derivable, assume it is false
- ▶ Semantically, prefer *minimal models*: a model  $I$  of  $P$  is *minimal*, if no model  $J \subseteq I$  of  $P$  exists.

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### Example: CWA on mutual recursion

$$P = \{ a \leftarrow b. \quad b \leftarrow a. \},$$

- ▶  $I = HB = \{a, b\}$  is a model (if  $P$  has no constraints)
- ▶ the minimal model is  $I = \emptyset$

# Answer Sets

## Guiding Idea

- ▶ rules must be obeyed (= model)
- ▶ model must be generated by firing rules
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## FLP-Reduct

The *FLP-reduct*  $P^I$  of a ground program  $P$  wrt. an interpretation  $I$  is obtained as follows: delete from  $P$  all rules  $r$  with false bodies:

$$P^I = \{r \in \text{grnd}(P) \mid I \models \text{body}(r)\}.$$

Answer sets of a program  $P$  are then defined as follows:

## Answer Set

An interpretation  $I$  is an *answer set* of  $P$ , if  $I$  is a minimal model of  $P^I$ .

# Answer Sets (cont'd)

## Example: Restaurant

program  $P$ :

$r_1$  :  $restaurant(osteria).$

$r_2$  :  $indoor(osteria) \leftarrow restaurant(osteria), not outdoor(osteria).$

# Answer Sets (cont'd)

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- ▶  $I_1 = \{restaurant(osteria), indoor(osteria)\}$ : answer set ✓

$$reduct P^I = \{r_1, r_2\} = P$$



# Answer Sets (cont'd)

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program  $P$ :

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$r_2$  :  $\text{indoor}(\text{osteria}) \leftarrow \text{restaurant}(\text{osteria}), \text{not } \text{outdoor}(\text{osteria}).$

▶  $I_1 = \{\text{restaurant}(\text{osteria}), \text{indoor}(\text{osteria})\}$ : answer set ✓

$\text{reduct } P^I = \{r_1, r_2\} = P$

▶  $I_2 = \{\text{restaurant}(\text{osteria}), \text{outdoor}(\text{osteria})\}$ : no answer set ✗

$\text{reduct } P^I = \{r_1\}$

# Answer Sets (cont'd)

## Example: Restaurant with Decision Making

- $r_1$   $\text{restaurant}(\text{osteria}).$
- $r_2$   $\text{indoor}(\text{osteria}) \vee \text{outdoor}(\text{osteria}) \leftarrow \text{restaurant}(\text{osteria}).$
- $r_3$   $\text{eat}(\text{osteria}) \leftarrow \text{indoor}(\text{osteria}), \text{raining}.$
- $r_4$   $\text{eat}(\text{osteria}) \leftarrow \text{outdoor}(\text{osteria}), \text{not raining}.$

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answer sets:

- ▶  $I_1 = \{\text{restaurant(osteria)}, \text{indoor(osteria)}\}$  ✓  
reduct  $P^{I_1} = \{r_1, r_2\}$
- ▶  $I_2 = \{\text{restaurant(osteria)}, \text{outdoor(osteria)}, \text{eat(osteria)}\}$  ✓  
reduct  $P^{I_2} = \{r_1, r_2, r_4\}$
- ▶  $I_3 = \{\text{restaurant(osteria)}, \text{indoor(osteria)}, \text{raining}\}$  ✗  
reduct  $P^{I_3} = \{r_1, r_2, r_3\}$
- ▶ all other  $I$ : ✗

# Non-Ground Programs

## General Case: Variable Elimination (*Grounding*)

*(ground) substitution*: mapping  $\sigma : \mathcal{X} \cup \mathcal{C} \rightarrow \mathcal{C}$  s.t.  $\sigma(c) = c$  for any  $c \in \mathcal{C}$

The *grounding* of (i) a rule  $r$  is  $grnd(r) = \{r\sigma \mid \sigma \text{ is a substitution}\}$ ;  
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## Example

- ▶  $P$   
 $reach(X, Y) \leftarrow conn(X, Y).$   
 $reach(X, Z) \leftarrow reach(X, Y), reach(Y, Z).$

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- ▶  $P' = P \cup \{conn(a, b). \quad conn(b, a). \}$

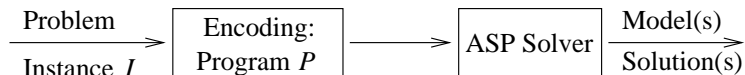
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answer set  $I = \{conn(a, b), conn(b, a), reach(a, b), reach(b, c), reach(a, c)\}$

# ASP Paradigm

## General idea: answer sets are solutions!

Reduce solving a problem instance  $I$  to computing answer sets of an LP



### ▶ Method:

1. *encode*  $I$  as a (non-monotonic) logic program  $P$ , such that solutions of  $I$  are represented by models of  $P$
2. *compute* some model  $M$  of  $P$ , using an ASP solver
3. *extract* a solution for  $I$  from  $M$ .

variant: compute multiple/all models (for multiple/all solutions)

- ▶ Often: decompose  $I$  into *problem specification* and *data*
- ▶ Use a *guess and check* approach

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# Lack of Answer Sets: Incoherence

Programs with not might lack answer sets.

## Example

$$P = \{ p \leftarrow \text{not } p. \}$$

NO answer set is possible (“derive  $p$  if it is not derivable”)

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*man(bertrand).*

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*shaves(X, Y) ← barber(X), man(Y), not shaves(Y, Y).*

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- ▶ Adding  $p \leftarrow q_1, \dots, q_m, \text{not } r_1, \dots, \text{not } r_n, \text{not } p.$   
to  $P$ , where  $p$  is fresh, “kills” all answer sets of  $P$  that (i) contain  $q_1, \dots, q_m$ , and (ii) do not contain  $r_1, \dots, r_n$ .
- ▶ This is equivalent to the constraint  $\leftarrow q_1, \dots, q_m, \text{not } r_1, \dots, \text{not } r_n.$

# Incomparability and Minimality

- ▶ Answer sets are minimal models of  $P^I$ .
- ▶ What about  $P$  itself?

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## Proposition (Incomparability)

*If  $I$  is an answer set  $I$  of a program  $P$ , then  $I \models P$  and no answer set  $I' \subset I$  of  $P$  exists (i.e., with  $I' \subseteq I$  s.t.  $I' \neq I$ ).*

## Example

- ▶  $P = \{a \leftarrow \text{not } b\}$ , answer set  $I = \{a\}$
- ▶  $P = \{a \leftarrow \text{not } b; \quad b \leftarrow \text{not } a;\}$ , answer sets  $I_1 = \{a\}$ ,  $I_2 = \{b\}$

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In fact, answer sets satisfy a stronger property in the spirit of CWA:

## Proposition (Minimality)

*Every answer set  $I$  of a program  $P$  is a minimal model of  $P$ .*

# Non-Monotonicity

Answer sets violate the monotonicity of classical logic

## Proposition (Non-monotonicity)

*Given some programs  $P, P'$  and an atom  $a$ , that  $I \models a$  for every answer set of  $P$  does not imply that  $I \models a$  for every answer set of  $P \cup P'$ .*

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## Example: Plain Restaurant

- ▶ restaurant program  $P$ :

$restaurant(osteria).$

$indoor(osteria) \leftarrow restaurant(osteria),$  not  $outdoor(osteria).$

answer set

$I = \{restaurant(osteria), indoor(osteria)\} \models indoor(osteria)$

- ▶  $P \cup \{outdoor(osteria)\}$  has the answer set

$I = \{restaurant(osteria), outdoor(osteria)\} \not\models indoor(osteria)$

Can be exploited to declare default behaviour!



# Supportedness

Presence of atoms in answer sets must be supported by rules

## Example

- ▶ rule  $r : a \leftarrow b, \text{not } c$ , model  $I = \{a, b\}$
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## Example (cont'd)

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But: stable  $\neq$  minimal + supported!

## Example

$$P = \{a \leftarrow a; \quad a \leftarrow \text{not } a\}$$

# Computational Complexity

An answer set program  $P$  is *normal*, if each rule  $r \in P$  is *normal*, defined as  $|head(r)| \leq 1$ .

## Theorem

*Deciding whether a normal program  $P$  has some answer set is*

- ▶ NP-complete in the ground (propositional) case;
- ▶ NEXPTIME-complete in the non-ground case.

## Theorem

*Deciding whether an answer set program  $P$  has some answer set is*

- ▶  $\Sigma_2^P$ -complete in the propositional case ( $\Sigma_2^P = \text{NP}^{\text{NP}}$ );
- ▶  $\text{NEXPTIME}^{\text{NP}}$ -complete in the non-ground case.

Note: the relational (i.e., function-free) non-ground case as considered here is also called *datalog case*

More on complexity: [Dantsin *et al.*, 2001]

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# Extensions of ASP

Language extensions like aggregates, complex formula syntax are within same semantic / computational framework

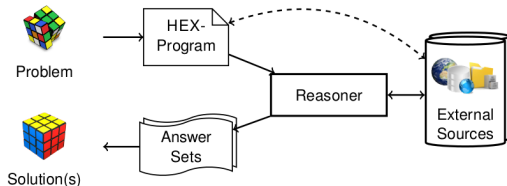
## Need

- ▶ interoperability with other logics, e.g. Description Logics
- ▶ interfacing with programming languages, e.g. C++, Python
- ▶ access to general *external* sources of information, e.g. WordNet

## Approaches

- ▶ embedded ASP: akin to embedded SQL
- ▶ bilateral interaction: e.g. JASP
- ▶ ASP + concrete theories: constraint ASP, ASP + ontologies
- ▶ *ASP + abstract theories*: clingo, [HEX/ DLVHEX](#)

# External Information Access



## Examples

- ▶ import external RDF triples into the program

$triple(S, P, O) \leftarrow \&rdf[\"http://\langle Nick \rangle.livejournal.com/data/foaf\"](S, P, O).$

- ▶ access external graph

$reachable(X) \leftarrow \&reachable[conn, a](X).$

- ▶ perform auxiliary / data structure computations

$fullname(Z) \leftarrow \&concat[X, Y](Z), firstname(X), lastname(Y).$

# External Information Access (cont'd)

## Issues



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- ▶ **Formal Model of External Atoms**
  - ▶ predicate input
  - ▶ allow arbitrary external code
    - ⇒ “impedance mismatch”

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  - ▶ e.g. cyclic reference (web graphs!)
  - ▶ non-monotonic external sources
    - ⇒ no simple fixpoint computation

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  - ▶ e.g. cyclic reference (web graphs!)
  - ▶ non-monotonic external sources
    - ⇒ no simple fixpoint computation
- ▶ **Value Invention**
  - ▶ new ground terms might appear

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# Syntax

New element:  $\mathcal{G}$  external predicate names  $\&g$  that have  $in(\&g)$  many “input” arguments and  $out(\&g)$  many “output” arguments

## External Atom

An *external atom* over a rel. signature  $S = (\mathcal{C}, \mathcal{P}, \mathcal{X}, \mathcal{G})$  is of the form

$$\&g[Y_1, \dots, Y_n](X_1, \dots, X_m)$$

where

- ▶  $Y_1, \dots, Y_n$  are terms and predicate names from  $\mathcal{C} \cup \mathcal{X} \cup \mathcal{P}$  (*input list*)
- ▶  $X_1, \dots, X_m$  are terms from  $\mathcal{C} \cup \mathcal{X}$  (*output list*)
- ▶  $\&g \in \mathcal{G}$  is an external predicate name with  $in(\&g) = n$ ,  $out(\&g) = m$

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## Examples

- ▶  $\&rdf[U](S, P, O)$ : intuitively, from a given concrete “input” URL  $U$  (a constant), retrieve (one by one) all “output” triples  $(S, P, O)$
- ▶  $\&reachable[connection, a](X)$ : intuitively, all nodes  $X$  reachable from node  $a$  in a graph represented by atoms of form  $connection(u, v)$ .

# External Atoms

## Examples (cont'd)

- ▶  $\&concat[X, Y](Z)$ : intuitively, concatenate two strings
  - ▶  $\&concat[bob, dylan](bobdylan)$  is true
  - ▶  $\&concat[bob, dylan](Z)$  is true for  $Z = bobdylan$
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External atoms can be of any nature (non-logical) nature

## Example

$\&weatherreport[dateLocationPredicate](WeatherConditions)$

query a web-based weather report

- ▶ input  $dateLocationPredicate$  is a binary predicate with tuples  $(d, l)$  of dates  $d$  and locations  $l$  (facts  $dateLocationPredicate(d, l)$ )
- ▶ output  $WeatherConditions$  are (one by one) all weather conditions that occur at some input date & location

$\&weatherreport[goto](W)$  where  $goto = \{(1, paris), (1, london), (2, paris), (2, london)\}$  returns all weather conditions on dates 1/2 for London/Paris



# HEX Programs

## HEX rule and program

A *HEX program* is a set  $P$  of (*HEX*) *rules*  $r$  of the form

$$A_1 \vee \dots \vee A_m \leftarrow L_1, \dots, L_n, \quad m, n \geq 0,$$

where all  $A_i$  are atoms, and all  $L_j$  are either literals or HEX-literals, i.e. either

- ▶ an ordinary literal,
- ▶ an external atom,
- ▶ or a default-negated external atom.

That is, like ordinary ASP rules/programs but external atoms can occur in rule bodies

## Examples

- ▶  $reachable(X) \leftarrow \&reachable[connection, a](X).$
- ▶  $fullname(Z) \leftarrow \&concat[X, Y](Z), firstname(X), lastname(Y).$
- ▶  $\leftarrow \&weatherreport[goto](W), badweather(W).$

# HEX Programs (cont'd)

## Example: City Trip

Plan to visit Paris and London, under the condition the weather isn't bad

Program  $\Pi_{goto}$ :

$$\begin{array}{ll} r_1 & \text{badweather}(rain). \quad \text{badweather}(snow). \\ r_2 & \text{goto}(1, \text{paris}) \vee \text{goto}(1, \text{london}). \\ r_3 & \text{goto}(2, \text{paris}) \vee \text{goto}(2, \text{london}). \\ r_4 & \leftarrow \& \text{weatherreport}[\text{goto}](W), \text{badweather}(W). \end{array}$$

- ▶ state what bad weather means ( $r_1$ )
- ▶ decide on what day to go to which city ( $r_2, r_3$ )
- ▶ exclude trips where the (external) weather report indicates bad weather during the trip ( $r_4$ )

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# Semantics

Analogous to ordinary ASP:

- ▶ the *Herbrand base*  $HB$  for HEX program  $P$
- ▶ the *grounding* of a rule  $r$ ,  $grnd(r)$ , and of  $P$ ,  $grnd(P) = \bigcup_{r \in P} grnd(r)$ .
- ▶ *interpretations* are subsets  $I \subseteq HB$  with no external atoms

To define satisfaction, key issue is the semantics of external atoms.

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## Oracle Function

Every  $\&g \in \mathcal{G}$ , has an associated decidable *oracle function*

$$f_{\&g} : 2^{HB_P} \times (\mathcal{C} \cup \mathcal{P})^n \times \mathcal{C}^m \rightarrow \{\mathbf{T}, \mathbf{F}\}, \quad n = in(\&g), m = out(\&g)$$

that maps each  $(I, \vec{y}, \vec{x})$ , where  $I \subseteq HB$  is an interpretation,  $\vec{y} = y_1, \dots, y_n$  on  $\mathcal{C} \cup \mathcal{P}$  is “input”, and  $\vec{x} = x_1, \dots, x_m$  on  $\mathcal{C}$  is “output”, to  $\mathbf{T}$  or  $\mathbf{F}$ .

Pragmatic assumptions:

- ▶ for any  $I, \vec{y}$ , only finitely many  $\vec{x}$  yield  $f_{\&g}(I, \vec{y}, \vec{x}) = \mathbf{T}$
- ▶ output  $\vec{x}$  is independent of the extensions of the predicates that do not occur in the input  $\vec{y}$

# Oracle Functions

## Example: String Concatenation

for the external predicate  $\&concat$ , the associated function is

$$f_{\&concat}(I, X, Y, Z) = \begin{cases} \mathbf{T}, & \text{if } XY = Z; \\ \mathbf{F}, & \text{otherwise} \end{cases}$$

(where  $XY$  is concatenation of  $X$  and  $Y$ )

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## Example: City Trip (cont'd)

- ▶ weather forecast Paris: sun on day 1 and day 2
- ▶ weather forecast London: rain on day 1 and day 2

the corresponding oracle function is ( $wr = \text{weatherreport}$ )

$$f_{\&wr}(I, goto, W) = \begin{cases} \mathbf{T}, & \text{if } \{goto(1, london), goto(2, london)\} \subseteq I \text{ and } W = \text{rain}, \\ \mathbf{T}, & \text{if } \{goto(1, london), goto(2, paris)\} \subseteq I \text{ and } W \in \{\text{sun}, \text{rain}\}, \\ \mathbf{T}, & \text{if } \{goto(1, paris), goto(2, london)\} \subseteq I \text{ and } W \in \{\text{sun}, \text{rain}\}, \\ \mathbf{T}, & \text{if } \{goto(1, paris), goto(2, paris)\} \subseteq I \text{ and } W = \text{sun}, \\ \mathbf{F}, & \text{otherwise.} \end{cases}$$

# Satisfaction and Models

## Satisfaction of External Atom

An interpretation  $I \subseteq HB$  *satisfies* (is a *model* of) a ground external atom  $a = \&g[\vec{y}](\vec{x})$ , denoted  $I \models a$ , if  $f_{\&g}(I, \vec{y}, \vec{x}) = \mathbf{T}$ .



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## Example: City Trip (cont'd)

For weather forecast as above:

- ▶  $I \models \&weatherreport[goto](sun)$  holds if  $I \models goto(1, paris)$ , or if  $I \models goto(2, paris)$ .
- ▶  $I \models \&weatherreport[goto](rain)$  if  $I \models goto(1, london)$  or if  $I \models goto(2, london)$ ,

# Answer Sets for HEX Programs

Answer sets naturally extend to HEX-programs

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An interpretation  $I \subseteq HB$  is an *answer set* of a HEX program  $P$ , if  $I$  is a minimal model of the *FLP-reduct*

$$P^I = \{r \in \text{grnd}(P) \mid I \models \text{body}(r)\}.$$

$AS(P)$  = the set of all answer sets of  $P$

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An interpretation  $I \subseteq HB$  is an *answer set* of a HEX program  $P$ , if  $I$  is a minimal model of the *FLP-reduct*

$$P^I = \{r \in \text{grnd}(P) \mid I \models \text{body}(r)\}.$$

$AS(P)$  = the set of all answer sets of  $P$

### Remarks:

- ▶ For ordinary  $P$  (no external atoms), the answer sets are as usual
- ▶ For aggregates modeled as external atoms (e.g.  $\&\text{count}[\text{goto}](N)$ ), the answer sets coincide with FLP-answer sets [Faber *et al.*, 2011]
- ▶ Alternative (more restrictive) notions of answer sets exist [Shen *et al.*, 2014]

# Answer Sets for HEX Programs

## Example: City Trip (cont'd)

$$\begin{aligned} \Pi_{goto} \quad & \text{badweather}(\text{rain}). \quad \text{badweather}(\text{snow}). \\ & \text{goto}(1, \text{paris}) \vee \text{goto}(1, \text{london}). \\ & \text{goto}(2, \text{paris}) \vee \text{goto}(2, \text{london}). \\ & \leftarrow \& \text{weatherreport}[\text{goto}](W), \text{badweather}(W). \end{aligned}$$

- ▶ For the above weather report,  $\Pi_{goto}$  has one answer set:  
 $\{\text{goto}(1, \text{paris}), \text{goto}(2, \text{paris}), \text{badweather}(\text{snow}), \text{badweather}(\text{rain})\}$

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- ▶ For a different weather report saying it's always sunny, 3 more answer sets exist:
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  - ▶  $\{\text{goto}(1, \text{london}), \text{goto}(2, \text{paris}), \text{badweather}(\text{snow}), \text{badweather}(\text{rain})\}$
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- ▶ Finally if the weather report for both cities is *snow* for days 1 and 2, no answer set exists.

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# Basic Properties

The basic properties of answer sets extend to HEX-programs:

- ▶ answer sets are incomparable
- ▶ answer sets are minimal models
- ▶ answer sets are supported models
- ▶ non-monotonicity

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- ▶ answer sets are supported models
- ▶ non-monotonicity

The computational complexity depends on external atoms: deciding answer set existence is

- ▶  $\Sigma_2^P$ -complete for ground programs, if evaluating external atoms, i.e. deciding whether  $f_{\&g}(I, \vec{y}, \vec{x}) = \mathbf{T}$  holds, is feasible in polynomial time with an NP oracle;
- ▶  $\Sigma_2^P$ -hard already for **Horn ground programs** (no disjunction, no negation) and **polynomial-time external atoms**.
- ▶ Thus, *minimality checking of answer set candidates for HEX-programs is a challenging problem*

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Modeling techniques from ordinary ASP carry over to HEX-programs.

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Consider a graph  $G = (V, E)$

given by facts  $node(v)$  for all  $v \in V$  and  $edge(u, v)$  for all  $(u, v) \in E$ .

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# Basic Methodology (cont'd)

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## Example: Non-3-Colorability of a Graph

$$\begin{aligned}b(X) \vee r(X) \vee g(X) &\leftarrow node(X) \\ non\_col &\leftarrow r(X), r(Y), edge(X, Y) \\ non\_col &\leftarrow g(X), g(Y), edge(X, Y) \\ non\_col &\leftarrow b(X), b(Y), edge(X, Y) \\ r(X) &\leftarrow non\_col, node(X) \\ g(X) &\leftarrow non\_col, node(X) \\ b(X) &\leftarrow non\_col, node(X)\end{aligned}$$

# Basic Methodology (cont'd)

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$$\begin{aligned} r(X) \vee g(X) \vee b(X) &\leftarrow node(X) \\ &\leftarrow not \&check[edge, r, g, b]() \end{aligned}$$

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# Methodology for Using External Atoms

## Main Usages of External Atoms

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- ▶ External sources may combine both use cases.
- ▶ **Important:** Both usages are based on the same language features!

# Computation Outsourcing

## On-demand Constrains

- ▶ Constraints of form

$\leftarrow \&forbidden[p_1, \dots, p_n]()$

eliminate certain extensions of predicates  $p_1, \dots, p_n$ .

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- ▶ **Example:**

Efficient planning in robotics where external atoms verify the feasibility of a 3D motion [Erdem *et al.*, 2016b].

# Computation Outsourcing (cont'd)

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## Complexity Lifting

- ▶ Computations with a complexity higher than the complexity of ordinary ASP programs.
- ▶ External sources can also be other ASP or HEX programs, which allows for encoding other formalisms of higher complexity in HEX programs, e.g., *abstract argumentation frameworks* [Dung, 1995].

# Information Outsourcing

## Data Sources

- ▶ RDF triplet stores:  
 $p(X, Y) \leftarrow url(U), \&rdf[U](X, Y, Z)$
- ▶ Geographic data
- ▶ Description logic ontologies
- ▶ Multi-context systems
- ▶ Relational databases

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### Note:

Some external sources may realize a combination of data and computation outsourcing (e.g. complex queries over ontologies).

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# Modeling an Application

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External atoms might be **reused** for multiple applications.

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# Applications of HEX-Programs

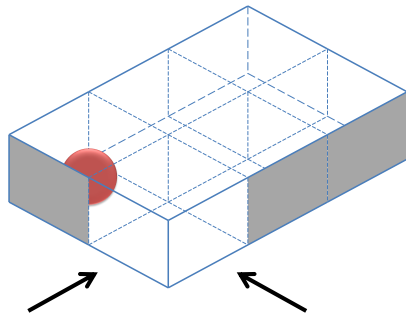
Some examples:

- ▶ **Queries of Web resources** (RDF triplet stores, social graphs, etc)
- ▶ **Multi-context Systems** (interconnection of knowledge-bases)
- ▶ **DL-programs** (integration of ASP with ontologies)
- ▶ **Constraint ASP** (programs with constraint atoms)
- ▶ **Physics simulation** (e.g. AngryBirds agent)
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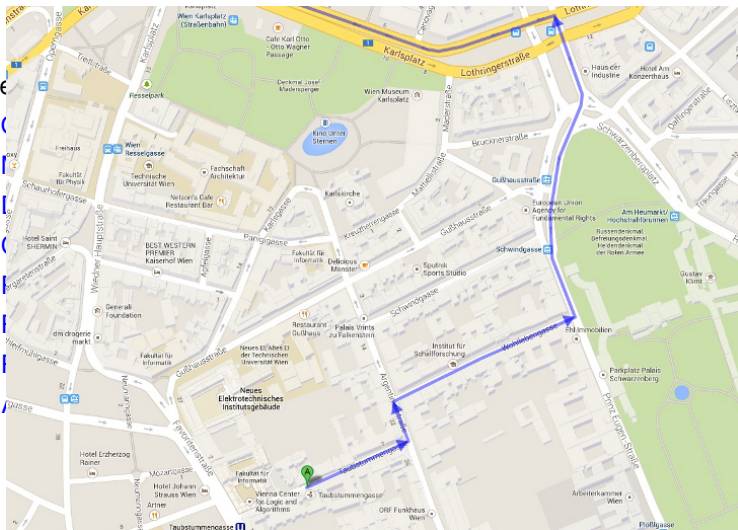
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# Example: Semantic Web Application

## Example: Friend-of-a-Friend

Use the FOAF (Friend-of-a-friend) RDF schema to return all pairs of nicknames that know each other, as stored in a FOAF RDF datasource:

```
explore("http://⟨Nick⟩.livejournal.com/data/foaf")  
triple(S, P, O) ← &rdf[What](S, P, O), explore(What)  
knows(Nick1, Nick2) ← triple(Id1, "http://xmlns.com/foaf/0.1/knows", Id2),  
    triple(Id1, "http://xmlns.com/foaf/0.1/nick", Nick1), Nick1 < Nick2,  
    triple(Id2, "http://xmlns.com/foaf/0.1/nick", Nick2).  
knows(A, C) ← knows(A, B), knows(B, C)
```



## Example: Semantic Web Application (cont'd)

### Example: Recursive FOAF querying with limited depth

```
explore("http://⟨Nick⟩.livejournal.com/data/foaf")  
explore_to(What, 3) ← explore(What)  
triple_at(S, P, O, D) ← &rdf[Uri](S, P, O), explore_to(Uri, D), D > 1  
explore_to(U, D2) ← D2 = D1 - 1,  
    triple_at(Id, "http://www.w3.org/2000/01/rdf-schema#seeAlso", U, D1),  
    triple_at(Id, "http://xmlns.com/foaf/0.1/nick", Nick, D1)  
found(Nick) ← triple_at(S, "http://xmlns.com/foaf/0.1/nick", Nick, D).
```

# Example: Physics Simulation

## Example: AngryHEX

### Fundamental strategy:

Maximize the estimated damage to obstacles and pigs.

$$\begin{aligned} \text{shootable}(O, \text{Type}, \text{Tr}) \leftarrow & \&\text{shootable}[O, \text{Tr}, V, Sx, Sy, Sw, Sh, B, bb](O), \\ & \text{birdType}(B), \text{velocity}(V), \text{objectType}(O, \text{Type}), \\ & \text{slingshot}(Sx, Sy, Sw, Sh), \text{trajectory}(\text{Tr}) \end{aligned}$$
$$\begin{aligned} \text{tgt}(O, \text{Tr}) \vee \text{ntgt}(O, \text{Tr}) \leftarrow & \text{shootable}(O, \text{Type}, \text{Tr}) \\ \leftarrow & \text{target}(X, -), \text{target}(Y, -), X \neq Y. \\ \leftarrow & \text{target}(-, T_1), \text{target}(-, T_2), T_1 \neq T_2 \end{aligned}$$
$$\begin{aligned} \text{target\_ex} \leftarrow & \text{target}(-, -) \\ \leftarrow & \text{not target\_ex}. \end{aligned}$$
$$\begin{aligned} \text{directDmg}(O, P, E) \leftarrow & \text{target}(O, \text{Tr}), \text{objectType}(O, T), \text{birdType}(\text{Bird}), \\ & \text{dmgProbability}(\text{Bird}, T, P), \\ & \text{energyLoss}(\text{Bird}, T, E) \end{aligned}$$

# Example: Physics Simulation

## Example: AngryHEX (cont'd)


$$\begin{aligned} exDirectDmg(O) &\leftarrow directDmg(O, -, -) \\ nexDirectDmg(O) &\leftarrow \text{not } exDirectDmg(O), objectType(O, -) \\ goodObject(O) &\leftarrow objectType(O, pig) \\ goodObject(O) &\leftarrow objectType(O, tnt) \\ \Leftarrow nexDirectDmg(O), goodObject(O) & \quad [1@4, O, nexDirectDmg] \\ \Leftarrow nexDirectDmg(O). & \quad [1@1, O, nexDirectDmg] \end{aligned}$$

# The DLVHEX-System



# DLVHEX

<http://www.kr.tuwien.ac.at/research/systems/dlvhex>

- ▶ Based on GRINGO and CLASP from the Potassco suite .
- ▶ Supported platforms: Linux-based, OS X, Windows.  
[Pre-compiled binaries](#) available.
- ▶ External sources are implemented as [plugins](#) using a [plugin API](#) (available for C++ or Python).
- ▶ Support for the [ASP-Core-2](#) standard.
- ▶ [Online demo](#):  
<http://www.kr.tuwien.ac.at/research/systems/dlvhex/demo.php>.
- ▶ [User manual](#) available (see system website).

# System Architecture

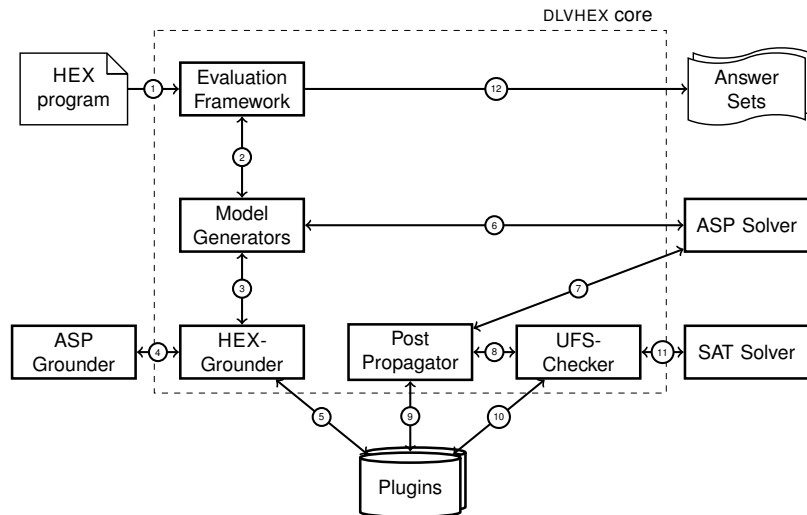


Figure: Architecture of DLVHEX

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# Python Programming Interface

## More convenient interface

Previously only C++ support, but Python preferred by many developers:

- ▶ No overhead due to makefiles, compilation, linking, etc.
- ▶ High-level features.
- ▶ Negligible overhead compared to plugins implemented in C++.

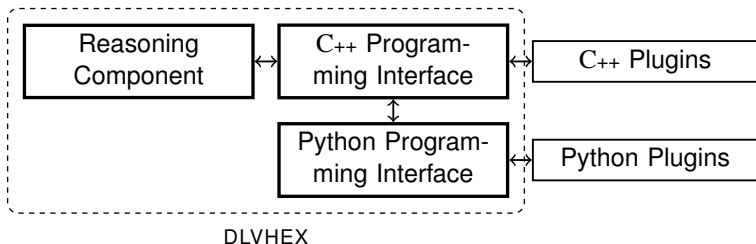


Figure: Architecture of the Python Programming Interface

# Python Programming Interface (cont'd)

## Example

Program

$$\Pi = \left\{ \begin{array}{l} r_1 : \text{start}(s). \\ r_2 : \text{reach}(X) \leftarrow \text{start}(X). \quad r_3 : \text{reach}(Y) \leftarrow \text{reach}(X), \&\text{edge}[X](Y). \end{array} \right\}$$

compute the nodes reachable from a start node  $s$  in a graph.

Implementation of  $\&\text{edge}[X](Y)$ :

```
def edge(x):
    graph = ((1, 2), (1, 3), (2, 3))           # simplified implementation
    for edge in graph:                       # search for out-edges of node x
        if edge[0] == x.intValue():
            dlvhex.output((edge[1],))        # output edge target

def register():
    prop = dlvhex.ExtSourceProperties()      # inform dlvhex about
    prop.addFiniteOutputDomain(0)          # finiteness of the graph
    dlvhex.addAtom("edge", (dlvhex.CONSTANT, ), 1, prop)
```



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# From Black-box to Grey-box

## Overcoming the Evaluation Bottleneck

- ▶ By default, external sources are seen as **black boxes**.
- ▶ Behavior under an interpretation does **not** allow for drawing conclusions about other interpretations.
- ▶ Algorithmic improvements require **meta-information about external sources**.

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## Idea

- ▶ **Developers of external sources** and/or **implementer of HEX-program** might have useful additional information.
- ▶ Provide a (predefined) list of **possible properties** of external sources.
- ▶ Let the developer and/or user **specify** which properties are satisfied.
- ▶ Algorithms **exploit** them for various purposes, most importantly:
  - ▶ **efficiency improvements** and
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## Important:

User specifies them but does **not** need to know how they are exploited!

# Specifying Properties

## Available properties (examples)

- ▶ **Functionality:**  $\&add[X, Y](Z) \langle \text{functional} \rangle$   
Adds integers  $X$  and  $Y$  and is true for their sum  $Z$ .  
It provides exactly one output for a given input.

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**Example:**

$\&greaterThan[p, 10]()$  is true if  $\sum_{p(c) \in I} c > 10$ .

It is monotonic for positive integers.

# Exploiting Properties for Efficiency Improvement

## Conflict-driven Solving

- ▶ ASP program is internally represented by **nogoods** (sets of literals which cannot be simultaneously true).
- ▶ Additional nogoods learned from **conflicting interpretations**.
- ▶ HEX-solver further **learns nogoods from external sources** which **describe parts of their behavior** to avoid future wrong guesses.

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## Example

- ▶ We evaluate  $\&diff[p, q](X)$  under  $I = \{p(a), q(b)\}$ .
- ▶ It is true for  $X = a$  (and false otherwise), i.e.,  $I \models \&diff[p, q](a)$ .
- ▶  $\Rightarrow$  Learn nogood  $N = \{p(a), \neg q(a), \neg p(b), q(b), \neg \&diff[p, q](a)\}$ .

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## Exploiting Properties

- ▶ Known properties used to **shrink nogoods to their essential part**.
- ▶ **Example:**  $\&diff[p, q](X)$  is monotonic in  $p$ :  
Shrink above nogood  $N$  to  $N' = \{p(a), \neg q(a), q(b), \neg \&diff[p, q](a)\}$ .  
(If  $p(b)$  turns to true,  $\&diff[p, q](a)$  is still true  $\Rightarrow \neg p(b)$  not needed.)

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## Grounding and Safety

- ▶ External atoms may introduce new constants: **value invention**.
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## Example

$$\Pi = \left\{ \begin{array}{l} r_1: \text{start}(s). \\ r_2: \text{reach}(X) \leftarrow \text{start}(X). \quad r_3: \text{reach}(Y) \leftarrow \text{reach}(X), \&edge[X](Y). \end{array} \right\}$$



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- ▶ But: **overly** restrictive.

## Exploiting Properties

- ▶ Properties may allow for **identifying finite groundability even in presence of recursive value invention** (in some cases).
- ▶ **Example:**

Known finiteness of the graph above allows for establishing safety.

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# Use Case: Semantic Trip Planning in Vienna



## Requirements

- ▶ Find **shortest trip** visiting predefined locations
- ▶ Long trip  $\Rightarrow$  add **lunch location** using an **ontology**
- ▶ Choose restaurant depending on **weather report**

*DEMO*

# Trip Planning

- ▶ Transport data might be:
  - ▶ Extremely large
  - ▶ Remote/not accessible
- ▶ Access external transport information  
([information outsourcing](#))
- ▶ Use dedicated algorithm to compute shortest connection  
([computation outsourcing](#))

External atom:

```
&route[File, Loc1, Loc2] (Stp1, Stp2, Costs, Line)
```

⇒ Obtain shortest trip by using [weak constraints](#)

*DEMO*



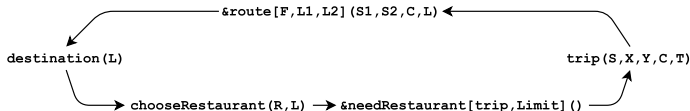
# Adding Lunch Location

- ▶ Adjustment of the trip based on its **length**
- ▶ Add **on-demand constraint** (no output needed)
- ▶ Boolean output depends **monotonically** on the input
  - ▶ Specify according property

External atom:

```
&needRestaurant [trip, Limit] ()
```

Introduces **cyclic dependency**, not strongly safe:



*DEMO*

# Partial Evaluation

- ▶ `&needRestaurant[trip, Limit]()` usually evaluated **only after** extension of `trip` is decided
  - ▶ Truth value not fixed before
- ▶ Often truth value can be decided early during search
- ▶ **Partial assignments**: atoms can be *true*, *false* or *unassigned*
- ▶ Use both methods `isTrue()` and `isFalse()`
  - ▶ Everything else is unassigned
- ▶ Use both methods `output()` and `outputUnknown()` to declare outputs
  - ▶ All other outputs are implicitly false
- ▶ Requirement: **assignment monotonicity**

## Example

Learned nogood:  $\{\neg t(0, 1), t(1, 1), t(2, 1), t(3, 1), \&nR[t, 3]()\}$

*DEMO*

# DL-Lite Plugin

- ▶ We use the DL-Lite Plugin for **semantically enriched route planning** (inspired by [Eiter *et al.*, 2016c])
- ▶ Interfaces to **OWL ontologies** using DL reasoner
- ▶ Provides external atoms for **concept** and **role** queries:
  - ▶  $\&cDL[File, rp, rm, cp, cm, C](X)$
  - ▶  $\&rDL[File, rp, rm, cp, cm, R](X, Y)$
- ▶ **Bidirectional interaction** by adding elements to concepts and roles, resp. to their complements

Link:

<http://www.kr.tuwien.ac.at/research/systems/dlvhex/dlliteplugin.html>

# Restaurant Ontology

*BeerGarden*  $\sqsubseteq$  *Restaurant*

*BeerGarden*  $\sqsubseteq$   $\neg$ *IndoorRestaurant*

*IndoorRestaurant*  $\sqsubseteq$  *Restaurant*

*IndoorRestaurant*  $\sqsubseteq$   $\neg$ *BeerGarden*

*IndoorRestaurant*  $\sqsubseteq$   $\neg$ *WurstStand*

*Restaurant*  $\sqsubseteq$   $\exists$ *closeTo*.*Location*

*WurstStand*  $\sqsubseteq$  *Restaurant*

*WurstStand*  $\sqsubseteq$   $\neg$ *IndoorRestaurant*

*Location*(*Karlsplatz*)

*Location*(*Museumsquartier*)

*Location*(*Praterstern*)

*BeerGarden*(*bg1*)

*closeTo*(*bg1*, *Praterstern*)

*IndoorRestaurant*(*ir1*)

*closeTo*(*ir1*, *Museumsquartier*)

*WurstStand*(*ws1*)

*closeTo*(*ws1*, *Karlsplatz*)

*DEMO*

# Weather Data

- ▶ Goal: retrieve **weather data** from `http://openweathermap.org/`
- ▶ Importing dynamic data from **remote location**
- ▶ **General plugin** for retrieving JSON data from API
  - ▶ Data represented by nested **key-value pairs**:  

```
{ "weather": [ { "id": 803, "main": "Clouds",  
                "description": "clouds", "icon": "04d" } ], ... }
```
- ▶ Input type `dlvhex.TUPLE` for **arbitrary number** of constants
  - ▶ Provide sequence of keys

External atom:

```
&getJSON[Url, Keys.TUPLE] (Value)
```



*DEMO*

# Summary of the Case Study

- ▶ Encoding uses four different external atoms **in combination**
  - ▶ `&route-Plugin` for **information** and **computation outsourcing**
  - ▶ `&needRestaurant-Plugin` for **external check**
  - ▶ `DL-Lite-Plugin` for interfacing an **external DL-reasoner**
  - ▶ `&getJSON-Plugin` for accessing **remote information** on the web
  
- ▶ Complete implementation and more examples at:  
<https://github.com/hexhex/manual/tree/master/RW2017/>

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# HEX<sup>∃</sup> Programs

- ▶ By **value invention** external atoms can generate **witnesses**
- ▶ Used to model **query answering** from existential rules

## Example

Not possible in standard ASP:

$$\exists X: \text{office}(Y, X) \leftarrow \text{employee}(Y).$$

Encoding with external atom:

$$\text{office}(Y, X) \leftarrow \text{employee}(Y), \&\text{exists}[r_1, Y](X).$$

# HEX Programs with Function Symbols

- ▶ External atoms can simulate **composition** and **decomposition** of function terms
- ▶ Allows external **data type checking** and **argument generation**

## Example

Not possible in standard ASP:

$$\begin{aligned}q(f(X)) &\leftarrow p(X). \\ r(Y) &\leftarrow q(f(Y)).\end{aligned}$$

Encoding with external atom:

$$\begin{aligned}q(A) &\leftarrow p(X), \&comp[f, X](A). \\ r(Y) &\leftarrow q(B), \&decomp[B](f, Y).\end{aligned}$$

# ACTHEX

- ▶ Extension of HEX for execution of **declaratively scheduled actions**
- ▶ **Action atoms** in rule heads operate on an **external environment**
- ▶ **Environment** can influence truth values of external atoms
  - ▶ Enables **stateful** behaviour

## Example

$$\begin{aligned} \#robot[clean, kitchen]\{c, 2\} &\leftarrow night \\ \#robot[clean, bedroom]\{c, 2\} &\leftarrow day \\ \#robot[goto, charger]\{b, 1\} &\leftarrow \&sensor[bat](low) \\ &night \vee day \leftarrow \end{aligned}$$

# Constraint HEX Programs

- ▶ **Grounding issues** when encoding constraints in ASP
- ▶ Contain ordinary, external and **constraint atoms**
  - ▶ Comparisons of **arithmetic expressions**
- ▶ Allow to combine diverse **background theories**

## Example

$$food(P) \leftarrow \&sql["\text{Select price from Food}"](P)$$
$$drink(P) \leftarrow \&sql["\text{Select price from Drink}"](P)$$
$$inMenu(F, D) \vee outMenu(F, D) \leftarrow food(F), drink(D)$$
$$F + D < P \leftarrow inMenu(F, D), max\_price(P)$$

Encoding of constraint with external atom:

$$con(F, +, D, <, P) \vee con(F, +, D, \geq, P) \leftarrow inMenu(F, D), max\_price(P) \\ \leftarrow \text{not } \&check[con]()$$

## Nested HEX [Eiter *et al.*, 2013]

- ▶ External atoms for **evaluating** subprograms and **inspecting** their answer sets:  
*&callhex*, *&callhexfile*, *&answersets*, *&predicates*, *&arguments*
- ▶ A new instance of DLVHEX is called and results stored in an **answer cache** assigning unique **handles**

### Example

$p_1(x, y) \leftarrow$

$p_2(a) \leftarrow$

$p_2(b) \leftarrow$

$handle(PH) \leftarrow \&callhexfile["sub.hex", p_1, p_2](PH)$

$ash(PH, AH) \leftarrow \&callhex["a \vee b :- "](PH), \&answersets[PH](AH)$



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# Related Work

- ▶ Many approaches, different **degrees of integration**
- ▶ DLV<sup>DB</sup> offers access to relational databases via *ODBC* interface
- ▶ ONTODLV for information retrieval from OWL ontologies, extends ASP with classes, inheritance, relations and axioms
- ▶ DLV-EX programs early **generic integration approach**
  - ▶ Introduction of new terms by **value invention**
  - ▶ Only terms as inputs to external sources
  - ▶ Nonmonotonic aggregates **not expressible**
- ▶ CLINGO supports custom functions implemented in *Lua* or *Python*
  - ▶ Import extensions of **user-defined** predicates during grounding
  - ▶ Customisable built-in atoms
  - ▶ **No cyclic dependencies**

## Related Work (cont'd)

- ▶ CLINGO 5 provides **generic interfaces** for theory solving in ASP
  - ▶ Semantics differs from HEX **unfounded support of theory atoms** allowed  $\Rightarrow$  consider  $p \leftarrow \&id[p]()$
  - ▶ Theory atoms interrelated via external theory (**orthogonal** to HEX)
  - ▶ No value invention based on answer set
  - ▶ Well-suited for system developers, **rich infrastructure**
  
- ▶ Extensions of ASP with specific external sources:
  - ▶ **Constraint ASP** solvers, e.g. CLINGCON, lc2casp, ezcsp, EZSMT
  - ▶ Extensions of **ASP with SMT**, e.g. dingo (difference logic), ASPMT

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# Summary

- ▶ HEX is a **powerful formalism**, wide range of applications
- ▶ Extends ASP with external sources via **API-style** interface
- ▶ **Bi-directional interaction** and **value invention** possible
- ▶ Methodology from ASP generalises to HEX
- ▶ Implemented in the DLVHEX system
  - ▶ Plugins in Python and C++
  - ▶ Exploiting **external source properties**



## DLVHEX

<http://www.kr.tuwien.ac.at/research/systems/dlvhex/>

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## Further Resources

- ▶ **All executable examples from this course:**  
<https://github.com/hexhex/manual/tree/master/RW2017/>
- ▶ **Slides of tutorial “ASP for the Semantic Web” and many executable ASP/HEX-examples:**  
<http://asptut.gibbi.com/>
- ▶ **An online demo of the DLVHEX system:**  
<http://www.kr.tuwien.ac.at/research/systems/dlvhex/demo.php>
- ▶ **Pre-built binaries of DLVHEX for Linux, OS X and Windows:**  
<http://www.kr.tuwien.ac.at/research/systems/dlvhex/downloadb.html>
- ▶ **The source code of DLVHEX and corresponding plugins, best place for bug reports:**  
<https://github.com/hexhex/>
- ▶ **Python-based HEX implementation for a fragment of the HEX language and a subset of features**  
<https://github.com/hexhex/hexlite>

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